## ML9484

Static, 1/2 Duty, 1/3 Duty, 1/4 Duty 50 Outputs LCD Driver

## GENERAL DESCRIPTION

The ML9484 is an LCD driver LSI, consists of a 50-bit shift register, a 200-bit data latch, 50 sets of LCD drivers, and a common signal generation circuit.
It can directly drive an LCD up to 50 segments for static display, 100 segments for 1/2-duty display, 150 segments for $1 / 3$-duty display, and 200 segments for $1 / 4$-duty display.

## FEATURES

- Logic power supply voltage :2.7 to 5.5 V
- LCD drive power supply voltage : 4.5 to 5.5 V
- Maximum number of segments

Static display $: 50$ segments
1/2-duty display : 100 segments
1/3-duty display $: 150$ segments
1/4-duty display $: 200$ segments

- Serially interfaces with the CPU using the three signal lines of DATA, CLOCK, and LOAD
- Selectable internal CR oscillator circuit or external clock input
- Built-in bias circuit
- Built-in common output intermediate-value voltage generation circuit
- Command-selectable A-waveform or B-waveform
- Package
: 64-pin plastic TQFP


## BLOCK DIAGRAM



## PIN CONFIGURATION (TOP VIEW)



64-Pin Plastic TQFP

## ABSOLUTE MAXIMUM RATINGS

| Item | Symbol | Condition | Rating | Unit |
| :--- | :---: | :---: | :---: | :---: |
| Logic power supply voltage | $\mathrm{V}_{\mathrm{DD}}$ | $\mathrm{Ta}=25^{\circ} \mathrm{C}$ | -0.3 to 6.0 | V |
| LCD drive power supply voltage | $\mathrm{V}_{\text {LCD }}$ | $\mathrm{Ta}=25^{\circ} \mathrm{C}$ | -0.3 to 6.0 | V |
| Input voltage | $\mathrm{V}_{\mathrm{I}}$ | $\mathrm{Ta}=25^{\circ} \mathrm{C}$ | -0.3 to $\mathrm{V}_{\mathrm{DD}}+0.3$ | V |
| Output short-circuit current | Is | $\mathrm{Ta}=25^{\circ} \mathrm{C}$ | -2.0 to +2.0 | mA |
| Power dissipation | $\mathrm{P}_{\mathrm{D}}$ | $\mathrm{Ta} \leqq 105^{\circ} \mathrm{C}$ | 145 | mW |
| Storage temperature | $\mathrm{T}_{\text {STG }}$ | - | -55 to +150 | ${ }^{\circ} \mathrm{C}$ |

Note: Do not use the ML9484 by short-circuiting one output pin to another output pin as well as to other pin (input pin, input/output pin, or power supply pin).

## RECOMMENDED OPERATION CONDITIONS

| Item | Symbol | Condition | Range | Unit |
| :--- | :---: | :---: | :---: | :---: |
| Logic power supply voltage | $\mathrm{V}_{\mathrm{DD}}{ }^{*}$ | - | 2.7 to 5.5 | V |
| LCD drive power supply voltage | $\mathrm{V}_{\mathrm{LCD}}{ }^{*}$ | - | 4.5 to 5.5 | V |
| OSC IN clock frequency | $\mathrm{f}_{\mathrm{CP} 1}$ | - | 0.5 to 10 | kHz |
| Data clock frequency | $\mathrm{f}_{\mathrm{CP} 2}$ | - | 0.01 to 1.0 | MHz |
| Operating temperature | $\mathrm{T}_{\mathrm{a}}$ | - | -40 to +105 | ${ }^{\circ} \mathrm{C}$ |

Note(*): Use at $\mathrm{V}_{\mathrm{DD}} \leq \mathrm{V}_{\mathrm{LCD}}$.

## ELECTRICAL CHARACTERISTICS

## DC Characteristics

| Item |  | Symbol | Condition | Min. | Typ. | Max. | Unit | Applicable pin |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| " H " input voltage |  | $\mathrm{V}_{\mathrm{IH}}$ | - | 0.8 VDD | - | $V_{D D}$ | V | (*1) |
| "L" input voltage |  | $\mathrm{V}_{\text {IL }}$ | - | GND | - | $0.2 \mathrm{~V}_{\mathrm{DD}}$ | V | (*1) |
| Input leakage current 1 |  | $\mathrm{L}_{\mathrm{L} 1}$ | $\mathrm{V}_{1}=\mathrm{V}_{\mathrm{DD}}$ or 0 V | -1 | - | 1 | $\mu \mathrm{A}$ | (*2) |
| Input leakage current 2 |  | $\mathrm{l}_{\mathrm{L} 2}$ | $V_{1}=V_{D D}$ | -1 | - | 1 | $\mu \mathrm{A}$ | RESETB |
| Pull-up current |  | $\mathrm{I}_{\mathrm{pu}}$ | $\mathrm{V}_{\mathrm{DD}}=5.0 \mathrm{~V}, \mathrm{~V}_{1}=0 \mathrm{~V}$ | 30 | - | 140 | $\mu \mathrm{A}$ | RESETB |
| Driver ON resistor | Segment | $V_{\text {OHS }}$ | $\mathrm{V}_{\text {LCD }}=5 \mathrm{~V}$ | - | 5 | 15 | k $\Omega$ | $\begin{aligned} & \hline \text { SEG1 to } \\ & \text { SEG50 } \\ & \hline \end{aligned}$ |
|  | Common | $\mathrm{V}_{\text {OHC }}$ | $\mathrm{V}_{\text {LCD }}=5 \mathrm{~V}$ | - | 5 | 12 | k $\Omega$ | $\text { COM } 1 \text { to }$ COM4 |
| Static supply current |  | Idds | $\mathrm{V}_{\mathrm{DD}}=\mathrm{V}_{\mathrm{LCD}}=5.5 \mathrm{~V}$ <br> Input pin fixed to " H " or "L" <br> Oscillation stopped, output no-load | - | 1 | 7 | $\mu \mathrm{A}$ | VDD |
|  |  | ILCDS |  | - | 9 | 15 | $\mu \mathrm{A}$ | VLCD |
| Dynamic supply current 1 |  | IDD1 | $\begin{aligned} & \mathrm{V}_{\mathrm{DD}}=\mathrm{V}_{\mathrm{LCD}}=5.5 \mathrm{~V}\left({ }^{* 3} 3\right) \\ & \text { Clock } \mathrm{OSC} \text { external input } \\ & \mathrm{f}_{\mathrm{CP} 1}=1.8 \mathrm{kHz} \end{aligned}$ | - | 2 | 10 | $\mu \mathrm{A}$ | VDD |
|  |  | lLCD1 |  | - | 9 | 15 | $\mu \mathrm{A}$ | VLCD |
| Dynamic supply current 2 |  | $\mathrm{l}_{\mathrm{DD} 2}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{DD}}=\mathrm{V}_{\mathrm{LCD}}=5.5 \mathrm{~V}(* 4) \\ & \text { Internal oscillation }=95 \mathrm{~Hz} \end{aligned}$ | - | 53 | 82 | $\mu \mathrm{A}$ | VDD |
|  |  | ILCD2 |  | - | 9 | 15 | $\mu \mathrm{A}$ | VLCD |

(*1) : DATA, CLOCK, LOAD, RESETB, OSC, OSC I/E
(*2): DATA, CLOCK, LOAD, OSC, OSC I/E
(*3): 1/4-duty, 1/3-bias, OSCI/E="L'", Output pin no-load.
(*4) : 1/4-duty, 1/3-bias, OSCI/E="H", (F2, F, F0) $=(0,1,1) 95 \mathrm{~Hz}$, Output pin no-load.

## Switching Characteristics

- OSC timing
$\left(\mathrm{V}_{\mathrm{DD}}=2.7\right.$ to $5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{LCD}}=4.5$ to $5.5 \mathrm{~V}, \mathrm{Ta}=-40$ to $+105^{\circ} \mathrm{C}$ )

| Item | Symbol | Condition | Min. | Typ. | Max. | Unit | Applicable pin |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| OSC IN clock frequency (External input) | $\mathrm{f}_{\mathrm{CP} 1}$ | Clock input from OSC. OSC I/E = "L" | 0.5 | 1.8 | 10 | kHz | OSC |
| Clock pulse width (External input) | twcP1 |  | 40 | - | - | $\mu \mathrm{s}$ | OSC |
| Clock rise and fall time (External input) | tosc |  | - | - | (*1) | $\mu \mathrm{s}$ | OSC |
| Internal clock frequency (Internal oscillation) | fosc1 | $\begin{aligned} & \text { OSC open. } \\ & \text { (F2, F1, FO)=(0, 0, 1) } \\ & \text { OSC I/E = "H" } \end{aligned}$ | 18 | 28.8 | 44 | kHz | OSC |

The relation between OSC IN clock frequency and frame frequency is as the equation below.

$$
\mathrm{f}_{\mathrm{FRM}}=\mathrm{f}_{\mathrm{CP} 1} / 24
$$

(*1) $t_{\text {OSC }}$ is a reference value.
The longer the clock rise and fall time, the more susceptible to extraneous noises around the threshold value. Make the rise as steep as possible. Reference value: $\max =2 \mu$ s.

- Serial interface timing
$\left(\mathrm{V}_{\mathrm{DD}}=2.7\right.$ to $5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{LCD}}=4.5$ to $5.5 \mathrm{~V}, \mathrm{Ta}=-40$ to $\left.+105^{\circ} \mathrm{C}\right)$

| Item | Symbol | Condition | Min. | Typ. | Max. | Unit | Applicable pin |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Data clock frequency | $\mathrm{f}_{\mathrm{CP} 2}$ |  | 0.01 | - | 1 | MHz | CLOCK |
| Data clock pulse width | twCP2 |  | 100 | - | - | ns | CLOCK |
| Data setup time | tsu |  | 50 | - | - | ns | DATA |
| Data hold time | $\mathrm{thD}^{\text {d }}$ |  | 50 | - | - | ns | CLOCK |
| CLOCK-LOAD timing | $\mathrm{t}_{\mathrm{CL}}$ |  | 100 | - | - | ns | CLOCK |
| LOAD-CLOCK timing | tLC |  | 100 | - | - | ns | LOAD |
| LOAD pulse width | twLD |  | 100 | - | - | ns | LOAD |
| Signal rise and fall time | tsr,tsf |  | - | - | (*2) | ns | CLOCK,DATA, LOAD |

(*2) tsr and tsf shall be reference values.
The longer the clock rise and fall time, the more susceptible to extraneous noises around the threshold value. Make the rise as steep as possible. Reference value: $\max =10 \mathrm{~ns}$.

Timing chart (OSC)


## Timing chart (Serial interface)



## POWER ON/OFF TIMING

To turn on the power supply, raise the logic power supply first, then LCD drive power supply in order to prevent the IC from malfunctioning.
To fall the power supply, fall the LCD drive power supply first, then the logic power supply.
For a VDD pin ranging from 0 V to VDDmin, set VDD $\geq \mathrm{VLCD}$ and $\mathrm{t} 1 \geq 0$ [ns].
Voltage


## INITIALIZATION SIGNAL TIMING

Keep the RESETB pin at "L" level until the VDD reaches VDD min. ( $\mathrm{t} 2 \geq 200$ [ns])


The value of the current of the pull-up resistor is specified for RESETB pin.
The customer needs to select an external capacitor that meets the timing requirements shown above.

## PIN DESCRIPTIONS

| Pad <br> number | Symbol | I/O | Description |
| :---: | :---: | :---: | :--- |
| 1 to 50 | SEG1 to <br> SEG50 | O | Outputs for LCD display. Connected to the segment pins on the LCD panel. <br> In the display off mode, all the outputs are fixed to GND. |
| 51 to 54 | COM1 to <br> COM4 | O | Outputs for LCD display. Connected to the common pins on the LCD panel. <br> In the display off mode, all the outputs are fixed to GND. |
| 55 | VLCD | - | Power supply pin for LCD driver. |

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## DESCRIPTION

## Operation description

- Display data input

As described in the Data configuration section, the display data consists of the data field that corresponds to each segment on/off and the command field that indicates the display data input.
When inputting the display data, the "F1" command is set in the command field. When the "F2" to "F5" command is set in the command field, the display data in the data field becomes invalid.
The data input to the DATA pin is loaded to the shift register at the CLOCK pulse rise, transferred to the display data latch during the LOAD pulse at the " H " level, then output via the segment driver.


- Display on, Display off

The display becomes off at power-on reset. To display, write the display on command.
The display off is the command that makes all segments off. Writing the display off command turns off the lights regardless of the display data.
The display on is the command to release the display off. Writing the display on command returns the display to the original state.


## List of Commands

| Command name | C5 | C4 | C3 | C2 | C1 | C0 | Operation |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| F0 | 0 | 0 | 0 | x | x | x | Disabled |
| F1 | 0 | 0 | 1 | Co1 | CoO | x | Data write address setting (Co1,Co0)=(0, 0): Corresponding to common 1 (Co1,Co0)=(0, 1): Corresponding to common 2 (Co1,Co0)=(1, 0): Corresponding to common 3 (Co1,Co0)=(1, 1): Corresponding to common 4 |
| F2 | 0 | 1 | 0 | $\begin{aligned} & \text { F2 } \\ & \text { (0) } \end{aligned}$ | $\begin{aligned} & \text { F1 } \\ & \text { (0) } \end{aligned}$ | $\begin{aligned} & \text { F0 } \\ & \text { (0) } \end{aligned}$ | Frame frequency setting (F2, F1, F0) $=(0,0,0): 65 \mathrm{~Hz}$ (F2, F1, F0) $=(0,0,1): 75 \mathrm{~Hz}$ (F2, F1, F0) $=(0,1,0): 85 \mathrm{~Hz}$ (F2, F1, F0) $=(0,1,1): 95 \mathrm{~Hz}$ (F2, F1, F0) $=(1,0,0): 130 \mathrm{~Hz}$ (F2, F1, F0) $=(1,0,1): 150 \mathrm{~Hz}$ (F2, F1, F0) $=(1,1,0): 170 \mathrm{~Hz}$ (F2, F1, F0) $=(1,1,1): 190 \mathrm{~Hz}$ (valid for Internal CR oscillation) |
| F3 | 0 | 1 | 1 | BIAS <br> (0) | WSEL <br> (0) | x | LCD Bias setting <br> BIAS="0" : 1/3-bias <br> BIAS="1": 1/2-bias <br> LCD Driving Waveform setting <br> WSEL="0" : A-Waveform <br> WSEL="1" : B-Waveform |
| F4 | 1 | 0 | 0 | $\begin{aligned} & \text { D1 } \\ & (0) \end{aligned}$ | $\begin{aligned} & \text { D0 } \\ & \text { (0) } \end{aligned}$ | x | Display Duty setting <br> (D1, D0) $=(0,0)$ : Static <br> (COM1=COM2=COM3=COM4) <br> (D1, D0) $=(0,1): 1 / 2$-duty <br> (COM1=COM3, COM2=COM4) <br> (D1, D0)=(1, 0): 1/3-duty <br> (COM2=COM4) <br> (D1, D0)=(1, 1): 1/4-duty |
| F5 | 1 | 0 | 1 | $\begin{gathered} \text { DSP } \\ (0) \end{gathered}$ | x | x | Display on/off setting <br> DSP="0": Off (COM=SEG=GND) <br> DSP="1": On |
| F6 | 1 | 1 | 0 | x | X | x | Disabled |
| F7 | 1 | 1 | 1 | x | x | x | Disabled |

x: Don't care
( ): Reset Value

## Data configuration

[Input data]
First bit
Corresponding to SEG50


Note 1: The commands F4 settings become valid when the least four bits of C2 to C5 are input.
(The bits from D1 to D50 and from C0 to C1 are not necessary.)
The commands F3 and F4 settings become valid when the least five bits of C1 to C5 are input. (The bits from D1 to D50 and from C0 are not necessary.)
The commands F2 settings become valid when the least six bits of C 0 to C 5 are input.
(The bits from D1 to D50 are not necessary.)
Note 2: If the dummy bit is needed for the reason of number of transfer bits, put it on the first bit side.
Note 3: The command execution follows the contents of the C 5 to C 0 registers immediately before the LOAD becomes "H".

## LCD Driving Waveform

- Static mode (same as A-waveform and B-waveform)

- 1/2-duty, 1/2-bias mode (A-waveform)

- 1/2-duty, 1/3-bias mode (A-waveform)

- 1/3-duty, 1/2-bias mode (A-waveform)

- 1/3-duty, 1/3-bias mode (A-waveform)

- 1/4-duty, 1/2-bias mode (A-waveform)

- 1/4-duty, 1/3-bias mode (A-waveform)

- 1/2-duty, 1/2-bias mode (B-waveform)

- 1/2-duty, 1/3-bias mode (B-waveform)

- 1/3-duty, 1/2-bias mode (B-waveform)

- 1/3-duty, 1/3-bias mode (B-waveform)

- 1/4-duty, 1/2-bias mode (B-waveform)

- 1/4-duty, 1/3-bias mode (B-waveform)



## EXAMPLE OF APPLICATION CIRCUIT



## REFRESH

Although the ML9484 holds operation state by commands, excessive external noise might change the internal state.
On a chip-mounting and system level, it is necessary to take countermeasures against preventing noise from occurring. It is recommended to use the refresh sequence periodically to control sudden noise.

## PACKAGE DIMENSIONS



Notes for Mounting the Surface Mount Type Package
The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact ROHM's responsible sales person for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

## REVISION HISTORY

| Document No. | Issue Date | Page |  | Description |
| :--- | :---: | :---: | :---: | :--- |
|  |  | Previous <br> Edition | New <br> Edition |  |
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[^0]:    *1: Reset circuit configuration

